

Navigation in Spinal Surgery

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Disclosures

- Consultant-Medtronic, SI bone

Goals of surgery

- Reproducibility
- Efficiency
- Completeness
- Safety

- Safety applies to patient, surgeon, and staff
- Ionizing radiation is a significant risk to all of us

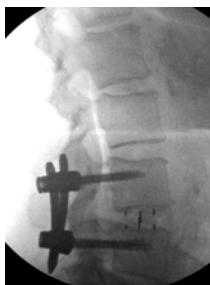
Hardware placement

- Significant component of spinal surgery
- Techniques
 - Anatomic
 - Fluoroscopy aided
 - Image guided
- Every surgeon should be comfortable with anatomy
- If you rely solely on technology, trouble will come when it isn't available

Pedicle screw placement

- Anatomy
 - Free hand technique- malpositioned screws 6% of the time
 - Best of hands (Lenke, Bridwell)
 - None of these screws required revision at 10 years
- Fast
- Limited radiation
- Excellent exposure for fusion

Is MIS possible without fluoro?



Why do we want to limit fluoro?

- Exposure to radiation
- Contamination of surgical field
- Systems are operator dependent (good tech??)
- Can be difficult with larger patients
- Ergonomics
- Lead is heavy!!!

History of Spinal Navigation

- First described in mid 1990's
 - Screw malposition rates up to 50% in thoracic spine
 - Usually not symptomatic
 - Malposition rates typically similar regardless of surgical technique
 - Developed in parallel with expansion of MIS
- Goals
 - Improve accuracy
 - Save time
 - Decrease radiation

Radiation

- Guidance offers improved dosages for OR staff and surgeon
 - 10-12X more radiation exposure to surgeon in spine cases
 - Essentially none with guidance
- More for the patient
 - 15X more radiation in CT based screw placement compared with fluoro based
 - If image guidance is used instead of pre-op CT, dose is similar
 - Less with 2 and 3 D fluoro systems

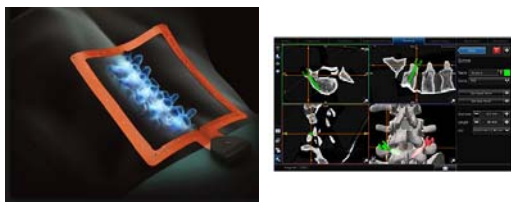
System Types

- Initial: CT based
 - Early systems required pre-op CT scan
 - Scan was uploaded to software in OR
 - Often slow and fickle
- Newer
 - IO CT scans
 - 2D, 3D fluoroscopy
 - IO MRI
 - Used in brain tumors
 - IO Ultrasound

Intraoperative Image Acquisition



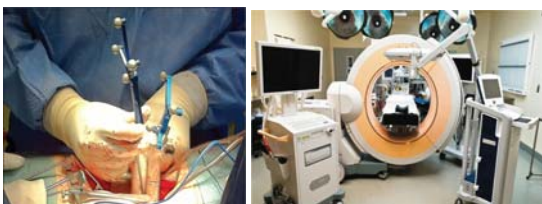
SpineMask



How systems work

- Acquire images with fixed reference point(s)
 - Accuracy compromised by movement
- Some systems allow reconfirmation with point arrays
- Surface markers allow for non invasive reference points
 - Affixed directly to guidance system
- Images uploaded; software processes
 - Images reconstructed and deconstructed
- Instruments and implants are loaded into the system
 - Then tracked by software

Optical Tracking



Electromagnetic field tracking



- Fiducials used
- Can also “surface mark”
- Less sensitive to obstruction

Accuracy of navigated screws

- Recent review of 20 studies (Shin, JNS 2012)
- 6% malposition rate in navigated screws
- 15% in “conventional” screw placement
- Neurologic complications rare
 - 3 in conventional group (3725 screws)
 - None in navigated group (4814 screws)

Getting closer to imageless reconciliation



Reconciliation- major limitation

- What we do to change anatomy is not accounted for
- Without new scans, software cannot update data
 - Surgeon must be aware
 - Evolution is toward overlay of pre-op and intra op films
- Possible solutions
 - Microtransmitters or fiducials
 - Active image acquisition (US??)
 - Surface onlay sheets show promise

Considerations for use in deformity

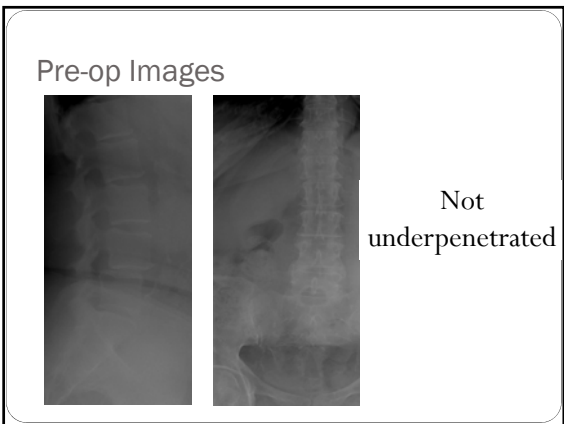
- Pre-operative planning as standard
 - Screws
 - Interbody
 - Osteotomies
- Anatomy altering steps are not processed by computer
- Can be used in truly MIS fashion, mini open, or open

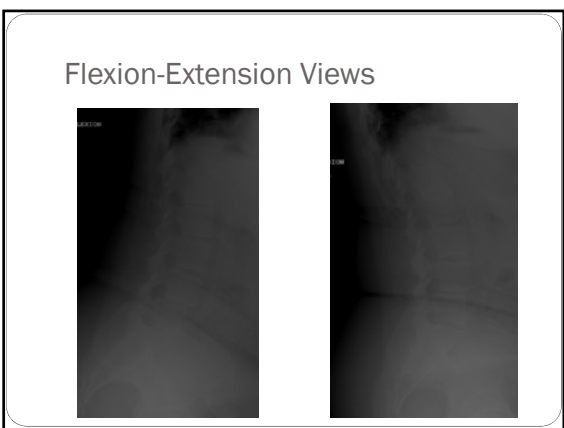
Interbodies

- TLIF, LLIF, OLIF, corpectomy cages can all be navigated
- For placement of multiple contiguous interbodies, begin cephalad and work caudal
 - If positioning or anatomy appear to change
 - Reconcile with surface referencing
 - Respin
 - Utilize fluoro
- If osteotomies are required, perform after interbody work
 - Consider fluoro or new scan
- Always place screws first

Case 1

- 60 year old female
- 5 feet tall, 170 pounds
- 5 year history of back and bilateral leg pain
 - Worse with walking, improved with laying and leaning back
- L LE 4/5 DF, Inversion, EHL
- No sensory deficit
- No nerve tension or long tract signs





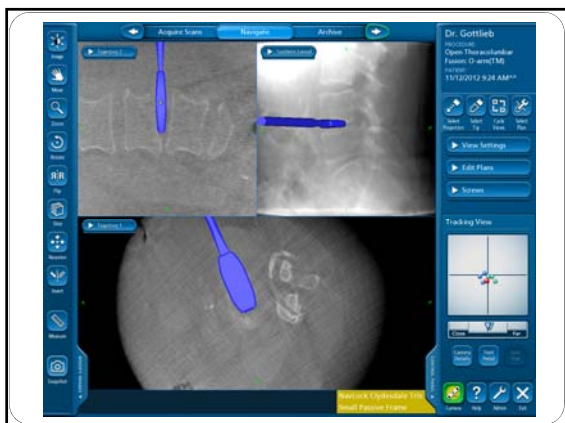


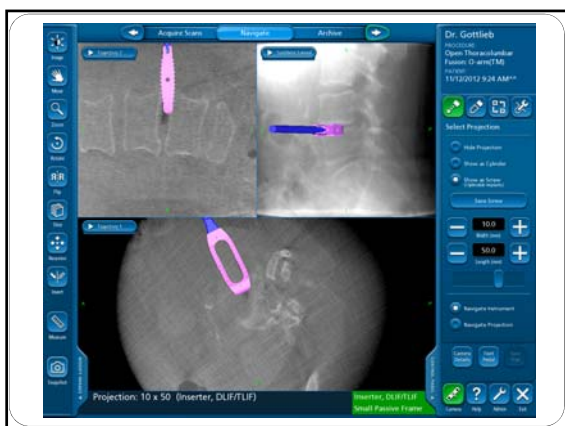
Surgical Plan

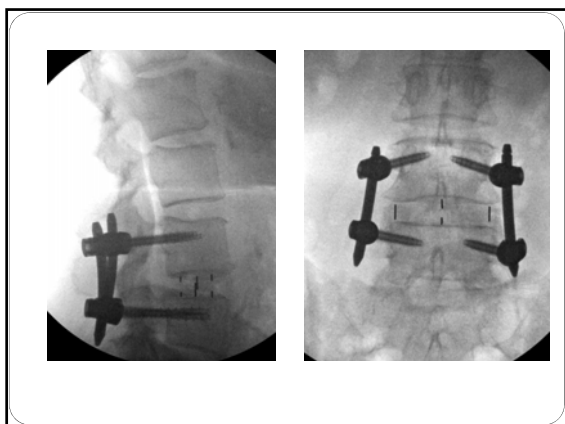
- OLIF (Oblique DLIF) L4-5
- Percutaneous pedicle screws
- O- arm guidance for interbody
 - Large patient
 - Fluoro will be difficult
- No decompression necessary
 - Slip reduces easily
 - Problem is dynamic (instability)











Clinical course

- 36 hours in the hospital
- Drove home to Key West from Miami
- Full return to activities

- Image guidance improved confidence during the procedure
- Struggles with imaging mitigated
